

#### 附錄四

由(4.17)式以及(4.18)式可知 $r_2^{NE}$ 、 $r_1^{NE}$ 為：

$$r_2^{NE} = \frac{1}{3} \left\{ \frac{A+B+2E+2F}{[(x_2-x_1)(1-\gamma hp - (1-\gamma)p) - z_2+z_1]} \right\} + \frac{1}{3} b_1 z_1 + \frac{2}{3} b_2 z_2 + \frac{1}{3} c_1 + \frac{2}{3} c_2 \quad \text{-----(4.17)}$$

$$r_1^{NE} = -\frac{1}{3} \left\{ \frac{A+B+2E+2F}{[(x_2-x_1)(1-\gamma hp - (1-\gamma)p) - z_2+z_1]} \right\} + \frac{A+B+E+F}{[(x_2-x_1)(1-\gamma hp - (1-\gamma)p) - z_2+z_1]} + \frac{2}{3} b_1 z_1 + \frac{1}{3} b_2 z_2 + \frac{2}{3} c_1 + \frac{1}{3} c_2 \quad \text{-----(4.18)}$$

其中：

A =

$$(x_2 - x_1) \left\{ (a_1 x_1 + K_1) \left[ (1 - \gamma)(1 - hp)^2 + (1 - p) \right] - (K_2 - K_1) \left[ (1 - p) - hp(1 - hp) \right] \right\}$$

B =

$$(-z_2 + z_1) \{ a_1 x_1 [(1 - hp) - \gamma p(1 - h)] + (K_2 - K_1) [-(1 - hp) + \gamma p(1 + h)] \}$$

E =

$$(x_2 - x_1) \{ [(1 - p)(1 + \gamma - hp)] [(a_2 x_2 + K_2) + (K_2 - K_1)] + \gamma (x_2 - x_1) [-\bar{y}p + \bar{y}hp] + [(x_2 - x_1)((\bar{y} - \bar{y}p) - z_2 + z_1)] [1 - \gamma hp] \}$$

F =

$$(-z_2 + z_1) \{ [-\gamma p + \gamma hp + 1 - hp] [(a_2 x_2 + K_2) + (K_2 - K_1)] + \gamma (x_2 - x_1) [-\bar{y}p + \bar{y}hp] + [(x_2 - x_1)((\bar{y} - \bar{y}hp) - z_2 + z_1)] \}$$

$$\therefore \frac{\partial r_2}{\partial z_1} =$$

$$\begin{aligned} & (18K_2 + 12hpK_2 + 6\gamma pK_2 - 24\gamma hpK_2 + 3K_1 + 12\gamma hpK_1 - 9\gamma h^2p^2K_2 \\ & - 24\gamma^2hp^2K_2 + 15\gamma^2h^2p^2K_2 - 6\gamma h^2p^2K_1 + 12\gamma^2hp^2K_1 - 9\gamma^2h^2p^2K_1 - 18pK_2 \\ & - 9hp^2K_2 - 9\gamma p^2K_2 + 24\gamma hp^2K_2 - 3hp^2K_1 - 6\gamma hp^2K_1 + 9\gamma^2p^2K_2 + 6(hp)^2K_1 \\ & - 9\gamma K_1 - 3(hp)^2K_2 + 12\gamma K_2 + 6\gamma pK_1 + 2hp^2K_2 - 6hp^2K_1) x_1 \\ & + (-18K_2 - 6\gamma pK_2 + 24\gamma hpK_2 - 3K_1 - 12\gamma hpK_1 + 9\gamma h^2p^2K_2 + 24\gamma^2hp^2K_2 \\ & - 15\gamma^2h^2p^2K_2 + 6\gamma h^2p^2K_1 - 12\gamma^2hp^2K_1 + 9\gamma^2h^2p^2K_1 + 18pK_2 + 9p^2K_2 \\ & + 9\gamma p^2K_2 - 24\gamma hp^2K_2 + 3hp^2K_1 - 3\gamma p^2K_1 + 6\gamma hp^2K_1 - 9\gamma^2p^2K_2 + 3\gamma^2p^2K_1 \\ & - 6(hp)^2K_1 + 9\gamma K_1 + 3(hp)^2K_2 - 6\gamma pK_1 - 12hp^2K_2 + 6hp^2K_1 - 12\gamma K_2) x_2 \end{aligned}$$

$$\begin{aligned}
& + (-18K_2 - 6hpK_1) z_1 \\
& + (18K_2 + 6hpK_1) z_2 \\
& + (-3hpa_1 + 6 - 12\gamma hp - 6\bar{y}hp - 6\gamma^2 hp^2 a_1 + 3\gamma^2 h^2 p^2 a_1 + 6\gamma^2 h^2 p^2 + 12\gamma^2 \bar{y}hp^2 \\
& - 6\gamma^2 \bar{y}h^2 p^2 + 6\bar{y}\gamma h^2 p^2 + 3pa_1 - 3hp^2 a_1 - 3\gamma p^2 a_1 + 6\gamma hp^2 a_1 - 6p + 6\gamma hp^2 \\
& + 6\gamma \bar{y}p^2 - 12\gamma \bar{y}hp^2 + 6\bar{y}hp^2 + 3\gamma^2 p^2 a_1 + 6\gamma p - 6\gamma^2 hp^2 - 6\gamma^2 \bar{y}p^2 - 6\gamma hp^2 \bar{y} \\
& + 3(hp)^2 a_1 - 3\gamma a_1 + 6\gamma hpa_1 + 6\gamma \bar{y}p) x_1^2 \\
& + (-6a_2 - 6\gamma a_2 + 6hpa_2 + 6pa_2 + 6\gamma pa_2 - 6hp^2 a_2 + 6\gamma \bar{y}p - 6\gamma \bar{y}hp - 6\bar{y} + 6\bar{y}p \\
& + 6\gamma hp \bar{y} - 6\gamma hp^2 \bar{y}) x_2^2 \\
& + 6z_1^2 \\
& + 6z_2^2 \\
& + (3hpa_1 - 6 + 12\gamma hp + 6\bar{y} + 6\bar{y}hp + 6\gamma h^2 p^2 a_1 + 6\gamma^2 hp^2 a_1 - 3\gamma^2 h^2 p^2 a_1 - 6\gamma^2 h^2 p^2 \\
& - 12\gamma^2 \bar{y}hp^2 + 6\gamma^2 \bar{y}h^2 p^2 - 6\bar{y}\gamma h^2 p^2 - 3pa_1 + 3hp^2 a_1 + 3\gamma p^2 a_1 - 6\gamma hp^2 a_1 + 6p \\
& - 6\gamma hp^2 - 6\gamma \bar{y}p^2 + 24\gamma \bar{y}hp^2 - 6\bar{y}p - 6\bar{y}hp^2 - 3\gamma^2 p^2 a_1 - 6\gamma p + 6\gamma^2 hp^2 + 6\gamma^2 \bar{y}p^2 \\
& - 3(hp)^2 a_1 + 3\gamma a_1 - 6\gamma hpa_1 - 12\gamma \bar{y}p + 6a_2 + 6\gamma a_2 - 6hpa_2 - 6pa_2 - 6\gamma pa_2 \\
& - 6hp^2 a_2) x_1 x_2 \\
& + (-12 + 12\gamma hp + 12p - 12\gamma p) x_1 z_1 \\
& + (12 - 12\gamma hp - 12p + 12\gamma p) x_1 z_2 \\
& + (6 - 6\gamma hp - 12p + 12\gamma p + 6\gamma pa_2 - 6\gamma hpa_2 - 6a_2 + 6hpa_2 + 6\gamma \bar{y}p - 6\gamma \bar{y}hp - 6\bar{y} \\
& + 6\bar{y}hp) x_2 z_1 \\
& + (-6 + 6\gamma hp + 12p - 12\gamma p - 6\gamma pa_2 + 6\gamma hpa_2 + 6a_2 - 6hpa_2 - 6\gamma \bar{y}p + 6\gamma \bar{y}hp \\
& + 6\bar{y} - 6\bar{y}hp) x_2 z_2 \\
& - 12 z_1 z_2 = 0 \text{ -----(4.24)}
\end{aligned}$$